#### Journal of Discrete Mathematics and Its Applications 8 (4) (2023) 177-185



Journal of Discrete Mathematics and Its Applications



Available Online at: http://jdma.sru.ac.ir

### Research Paper

# Vertex weighted Laplacian graph energy and other topological indices

# Reza Sharafdini; Habibeh Panahbar

Department of Mathematics, Faculty of Science, Persian Gulf University, Bushehr 7516913817, I. R. Iran

# Academic Editor: Farzaneh Nowroozi-Larki

**Abstract.** Let *G* be a graph with a vertex weight  $\omega$  and the vertices  $v_1, \ldots, v_n$ . The Laplacian matrix of *G* with respect to  $\omega$  is defined as  $L_{\omega}(G) = \text{diag}(\omega(v_1), \cdots, \omega(v_n)) - A(G)$ , where A(G) is the adjacency matrix of *G*. Let  $\mu_1, \cdots, \mu_n$  be eigenvalues of  $L_{\omega}(G)$ . Then the Laplacian energy of *G* with respect to  $\omega$  is defined as  $LE_{\omega}(G) = \sum_{i=1}^{n} |\mu_i - \overline{\omega}|$ , where  $\overline{\omega}$  is the average of  $\omega$ , i.e.,  $\overline{\omega} = \frac{\sum_{i=1}^{n} \omega(v_i)}{n}$ . In this paper, we consider several natural vertex weights of *G* and obtain some inequalities between the ordinary and Laplacian energies of *G* with corresponding vertex weights. Finally, we apply our results to the molecular graph of toroidal fullerenes (or achiral polyhex nanotorus).

**Keywords:** energy of graph, Laplacian energy, vertex weight, topological index, toroidal fullerenes. **Mathematics Subject Classification (2010):** Primary 05C90; Secondary 92E10.

## 1 Introduction

In this paper, we are concerned with simple graphs. Let *G* be a simple graph, with nonempty vertex set  $V(G) = \{v_1, ..., v_n\}$  and edge set  $E(G) = \{e_1, ..., e_m\}$ , that is to say, *G* is a simple (n,m)-graph. Let  $\omega$  be a vertex weight of *G*, i.e.,  $\omega$  is a function from V(G) to the set of positive real numbers. In this case, we say that *G* is a graph with a vertex weight  $\omega$ . A vertex weight  $\omega$  could be a constant function. In this case, we say *G* is  $\omega$ -regular. Namely, *G* 

<sup>\*</sup>Corresponding author (*Email address*: <a href="mailto:sharafdini@pgu.ac.ir">sharafdini@pgu.ac.ir</a>)

Received 24 October 2023; Revised 5 November 2023; Accepted 19 November 2023 First Publish Date: 1 December 2023

is  $\omega$ -regular if for any  $u, v \in V(G)$ ,  $\omega(u) = \omega(v)$ . Observe that a well-known vertex weight of a graph is the vertex degree assigning to each vertex its degree. Let us denote it by *deg*. The diagonal matrix of order *n* whose (i,i)-entry is  $\omega(v_i)$ , is called the diagonal vertex weight matrix of *G* with respect to  $\omega$  and is denoted by  $D_{\omega}(G)$ , i.e.,

$$D_{\omega}(G) = \operatorname{diag}(\omega(v_1),\ldots,\omega(v_n)).$$

The adjacency matrix  $A(G) = (a_{ij})$  of *G* is a (0,1)-matrix defined by  $a_{ij} = 1$ , if and only if the vertices  $v_i$  and  $v_j$  are adjacent. Then the matrices

$$L_{deg}(G) = D_{deg}(G) - A(G)$$
 and  $L_{deg}^{+}(G) = A(G) + D_{deg}(G)$ ,

are called Laplacian and signless Laplacian matrix of *G*, respectively (see [8,9,20–23]). These matrices were generalized for arbitrary vertex weighted graphs (see [27, 28]). Let *G* be a simple graph with the vertex weight  $\omega$ . Then we shall call the matrices

$$L_{\omega}(G) = D_{\omega}(G) - A(G)$$
 and  $L_{\omega}^{\dagger}(G) = A(G) + D_{\omega}(G)$ ,

the weighted Laplacian and the weighted signless Laplacian matrix of *G* with respect to the vertex weight  $\omega$ . Let  $X = \{x_1, x_2, ..., x_n\}$  be a data set of real numbers. The *mean absolute deviation* (often called the mean deviation) MD(X) and variance Var(X) of X is defined as

$$MD(X) = \frac{1}{n} \sum_{i=1}^{n} |x_i - \overline{x}|, \quad Var(X) = \frac{1}{n} \sum_{i=1}^{n} (x_i - \overline{x})^2,$$

where  $\overline{x} = \frac{\sum_{i=1}^{n} x_i}{n}$  is the arithmetic mean of the distribution. Note that an easy application of the Cauchy-Schwarz inequality gives that the mean deviation is a lower bound on the standard deviation (see [4]).

$$MD(X) \le \sqrt{Var(X)}.$$
 (1)

The mean deviation and variance of *G* with respect to  $\omega$ , denoted by  $MD_{\omega}(G)$  and  $Var_{\omega}(G)$ , respectively, is defined as

$$MD_{\omega}(G) = MD(\omega(v_1), \dots, \omega(v_n)), \quad Var_{\omega}(G) = Var(\omega(v_1), \dots, \omega(v_n)).$$

It follows from Eq. (1) that  $MD_{\omega}(G) \leq \sqrt{Var_{\omega}(G)}$ . It is worth mentioning that  $Var_{deg}(G)$  is a well-investigated graph invariant (see [3, 16]). Let  $\lambda_1, \lambda_2, ..., \lambda_n$  be eigenvalues of the adjacency matrix A(G) of graph G. It is known that  $\sum_{i=1}^{n} \lambda_i = 0$ . The notion of the energy  $\mathcal{E}(G)$  of an (n,m)-graph G was introduced by Gutman in connection with the  $\pi$ -molecular energy (see [10, 11, 14, 19]). It is defined as

$$\mathcal{E}(G) = \sum_{i=1}^{n} |\lambda_i| = n \mathrm{MD}(\lambda_1, \lambda_2, \dots, \lambda_n).$$

For details of the theory of graph energy see [11, 13, 26]. Let  $n \ge \mu_1, \mu_2, ..., \mu_n = 0$  be eigenvalues of Laplacian matrix  $L_{deg}(G)$  of graph *G*. It is known that  $\sum_{i=1}^{n} \mu_i = 2m$ . Gutman and Zhou defined the Laplacian energy of an (n, m)-graph *G* for the first time (see [15]) as

$$LE(G) = \sum_{i=1}^{n} \left| \mu_i - \frac{2m}{n} \right| = n \operatorname{MD}(\mu_1, \dots, \mu_n).$$

Numerous results on the Laplacian energy have been obtained, see for instance [2,6,7,12, 24,25,29]. Note that in the definition of Laplacian energy  $\frac{2m}{n}$  is the average vertex degree of *G*. This motivates us to extend their definition to the graphs equipped with an arbitrary vertex weight. Let *G* be a graph with the vertex set  $V = \{v_1, ..., v_n\}$  and with an arbitrary vertex weight  $\omega$ . Let  $\mu_1, \mu_2, ..., \mu_n$  be eigenvalues of the weighted Laplacian matrix  $L_{\omega}(G)$  of graph *G* with respect to the vertex weight  $\omega$ . Then we [27] proposed the Laplacian energy  $LE_{\omega}(G)$  of *G* with respect to the vertex weight  $\omega$  as

$$LE_{\omega}(G) = \sum_{i=1}^{n} \left| \mu_{i} - \overline{\omega} \right| = n \mathrm{MD}(\mu_{1}, \dots, \mu_{n}), \qquad (2)$$

where

$$\overline{\omega} = \frac{\sum_{i=1}^{n} \omega(v_i)}{n}$$
 and  $\sum_{i=1}^{n} \mu_i = n\overline{\omega}.$  (3)

Note that  $LE_{deg}(G) = LE(G)$ . Let *G* be a graph with an arbitrary vertex weight  $\omega$ . Some inequalities between  $\mathcal{E}(G)$  and  $LE_{\omega}(G)$  were established in [28]; and therein, the following three theorems were proved.

**Theorem 1.1.** Let G be a connected (n,m)-graph with a vertex weight  $\omega$ . Then

$$LE_{\omega}(G) \le nMD_{\omega}(G) + \mathcal{E}(G).$$
 (4)

Moreover, the equality in (4) holds if and only if G is  $\omega$ -regular.

**Theorem 1.2.** Let G be a bipartite graph with a vertex weight  $\omega$ . Then

$$LE_{\omega}(G) \ge \mathcal{E}(G).$$
 (5)

Moreover, the equality in (5) holds if and only if G is a  $\omega$ -regular graph.

**Theorem 1.3.** Let G be a bipartite (m,n)-graph with a vertex weight  $\omega$ . Then

$$\max\left\{n\mathrm{MD}_{\omega}(G),\mathcal{E}(G)\right\} \le LE_{\omega}(G) \le n\mathrm{MD}_{\omega}(G) + \mathcal{E}(G).$$
(6)

In this paper, we aim to apply the above theorems to graphs with some natural vertex weights and establish relationships between some graph invariants and Laplacian graph energy with respect to corresponding vertex weight.

#### 2 Main Results

Having a molecule, if we represent atoms by vertices and bonds by edges, we obtain a molecular graph. Graph theoretic invariants of molecular graphs, which predict properties of the corresponding molecule, are known as topological indices. The oldest topological index is the Wiener index, which was introduced in 1947. Since then, several topological indices have been proposed to predict characteristics of chemical compounds like physio-chemical, pharmacologic, toxicological and other biological properties. In this article, we deal with Wiener index, total eccentricity index and first Zagreb index.

#### 2.1 Wiener index

Let *G* be a connected graph. Given two vertices *u* and *v* in *V*(*G*), the distance between *u* and *v*, denoted by  $d(u,v) = d_G(u,v)$ , is the length of the shortest path connecting them. The Wiener index *W*(*G*) of a connected graph *G* is defined to be the sum of distances between any two unordered pair of vertices of *G*, i.e.

$$W(G) = \sum_{\{u,v\}\subseteq V(G)} d_G(u,v) = \frac{1}{2} \sum_{u,v\in V(G)} d_G(u,v).$$

The transmission Tr(v) of a vertex v is defined to be the sum of the distances from v to all other vertices in G [?], i.e.,

$$\operatorname{Tr}(v) = \sum_{u \in V(G)} d_G(u, v).$$

It is clear that

$$W(G) = \frac{1}{2} \sum_{v \in V(G)} \operatorname{Tr}(v).$$

A connected graph *G* is said to be *k*-transmission regular if Tr(v) = k for every vertex  $v \in V(G)$ . The transmission regular graphs are exactly the distance-balanced graphs introduced in [17]. They are also called self-median graphs [5]. We may consider the transmission of an arbitrary vertex as a vertex weight with the average  $\overline{\text{Tr}} = \frac{2W(G)}{n}$ . In this point of view, it follows from (2) that

$$LE_{\rm Tr}(G) = \sum_{i=1}^{n} \left| \mu_i - \frac{2W(G)}{n} \right| = n {\rm MD}(\mu_1, \dots, \mu_n).$$
(7)

**Theorem 2.1.** Let G be a connected graph with n vertices. Then the following hold:

(i)

$$LE_{\mathrm{Tr}}(G) \le n\mathrm{MD}_{\mathrm{Tr}}(G) + \mathcal{E}(G).$$
 (8)

(ii) If G is bipartite, then

$$LE_{\mathrm{Tr}}(G) \ge \mathcal{E}(G),$$
 (9)

$$\max\left\{n\mathrm{MD}_{\mathrm{Tr}}(G),\mathcal{E}(G)\right\} \le LE_{\mathrm{Tr}}(G).$$
(10)

Moreover, the equality in (8),(9) and (10) holds if and only if G is transmission regular.

*Proof.* Let *G* be a connected graph with *n* vertices. Then this theorem follows by applying Theorems 1.1,1.2,1.3 to *G* equipped with the vertex weight Tr and the fact that a graph is transmission regular if and only if it is Tr-regular.  $\Box$ 

#### 2.2 Zagreb indices

First Zagreb index of a graph *G* is defined as

$$M_1(G) = \sum_{u \in V(G)} deg_G(u)^2.$$

For a graph *G*, denote by t(u) the 2-degree of vertex *u*, which is the sum of the degrees of the vertices adjacent to *u*; a graph is said to be 2-degree regular if t(u) is constant for each *u*. It is known that

$$M_1(G) = \sum_{u \in V(G)} t(u),$$

We may consider the 2-degree of an arbitrary vertex as a vertex weight with the average  $\bar{t} = \frac{M_1(G)}{n}$ . In this point of view, it follows from (2) that

$$LE_t(G) = \sum_{i=1}^n \left| \mu_i - \frac{M_1(G)}{n} \right| = n \text{MD}(\mu_1, \dots, \mu_n).$$
(11)

**Theorem 2.2.** Let G be a connected graph with n vertices. Then the following hold:

(i)

$$LE_t(G) \le nMD_t(G) + \mathcal{E}(G).$$
 (12)

(ii) If G is bipartite, then

$$LE_t(G) \ge \mathcal{E}(G),$$
 (13)

$$\max\left\{n\mathrm{MD}_t(G), \mathcal{E}(G)\right\} \le LE_t(G). \tag{14}$$

Moreover, the equality in (12),(13) and (14) holds if and only if G is 2-degree regular.

*Proof.* Let *G* be a connected graph with *n* vertices. Then this theorem follows by applying Theorems 1.1,1.2,1.3 to *G* equipped with the vertex weight t and the fact that a graph is 2-degree regular if and only if it is *t*-regular.

Let us define  $deg^2(u) = deg_G(u)^2$ , the square vertex degree of u. So we may consider  $deg^2$  as a vertex weight of G with the average  $\overline{deg^2} = \frac{M_1(G)}{n}$ . From this point of view, a graph is square vertex degree regular if and only if it is vertex degree regular. In this point of view, it follows from (2) that

$$LE_{deg^{2}}(G) = \sum_{i=1}^{n} \left| \mu_{i} - \frac{M_{1}(G)}{n} \right| = n \operatorname{MD}(\mu_{1}, \dots, \mu_{n}).$$
(15)

**Theorem 2.3.** *Let G be a connected graph with n vertices. Then the following hold:* 

(i)

$$LE_{deg^2}(G) \le n \mathrm{MD}_{deg^2}(G) + \mathcal{E}(G).$$
(16)

(ii) If G is bipartite, then

$$LE_{deg^2}(G) \ge \mathcal{E}(G),\tag{17}$$

$$\max\left\{n\mathrm{MD}_{deg^2}(G), \mathcal{E}(G)\right\} \le LE_{deg^2}(G).$$
(18)

*Moreover, the equality in (17) and (18) holds if and only if G is vertex degree regular.* 

*Proof.* Let *G* be a connected graph with *n* vertices. Then this theorem follows by applying Theorems 1.1,1.2,1.3 to *G* equipped with the vertex weight deg<sup>2</sup> and the fact that a graph is vertex degree regular if and only if it is deg<sup>2</sup>-regular.

#### 2.3 Total eccentricity index

The eccentricity  $\varepsilon(u)$  of the vertex u of a connected graph G is the distance from u to any vertex farthest away from it in G, i.e.,  $\varepsilon(u) = \max_{v \in V(G)} d(u, v)$ . The maximum eccentricity over all vertices of G is called the diameter of G and is denoted by D(G); the minimum eccentricity among the vertices of G is called the radius of G and is denoted by R(G). The set of all vertices of minimum eccentricity is called the center of G. A connected graph G is called self-centred if  $\varepsilon(u) = R(G)$  for each  $u \in V(G)$ . The total eccentricity index of a connected graph G, denoted by  $\zeta(G)$ , is defined as the sum of eccentricities of vertices of G, i.e.,  $\zeta(G) = \sum_{u \in V(G)} \varepsilon(u)$ .

One may consider the eccentricity of a vertex as a vertex weight of *G* with the average  $\overline{\varepsilon} = \frac{\zeta(G)}{n}$ . From this point of view, a graph is  $\varepsilon$ -regular if and only if it is self-centred. In this point of view, it follows from (2) that

$$LE_{\varepsilon}(G) = \sum_{i=1}^{n} \left| \mu_i - \frac{\zeta(G)}{n} \right| = n \operatorname{MD}(\mu_1, \dots, \mu_n).$$
(19)

**Theorem 2.4.** Let G be a connected graph with n vertices. Then the following hold:

(i)

$$LE_{\varepsilon}(G) \le n MD_{\varepsilon}(G) + \mathcal{E}(G).$$
 (20)

(ii) If G is bipartite, then

$$LE_{\varepsilon}(G) \ge \mathcal{E}(G),$$
 (21)

$$\max\left\{n\mathrm{MD}_{\varepsilon}(G), \mathcal{E}(G)\right\} \le LE_{\varepsilon}(G).$$
(22)

Moreover, the equality in (20),(21) and (22) holds if and only if G is self-centred.

*Proof.* Let *G* be a connected graph with *n* vertices. Then this theorem follows by applying Theorems 1.1, 1.2, 1.3 to *G* equipped with the vertex weight  $\varepsilon$  and the fact that a graph is self-centred if and only if it is  $\varepsilon$ -regular.

Note that a tree is a connected bipartite graph. Therefore, in this paper, the hypothesis "connected bipartite graph" could be replaced by "Tree".

A graph *G* is called vertex-transitive if for every two vertices *u* and *v* of *G*, there exists an automorphism  $\sigma$  of *G*, such that  $\sigma(u) = \sigma(v)$ . It is known that any vertex-transitive graph is vertex degree regular, transmission regular and self-centred. Hence, it follows that

**Corollary 2.5.** Let G be a connected vertex-transitive graph. Then the equality holds in (8), (12), (17), (20). In fact,

$$\mathcal{E}(G) = LE_{\mathrm{Tr}}(G) = LE_t(G) = LE_{deg^2}(G) = LE_{deg}(G) = LE_{\varepsilon}(G).$$

A nanostructure is an object of intermediate size between molecular and microscopic structures. It is a product derived through engineering at the molecular scale. In what follows, we aim to apply Corollary 2.5 to the molecular graph of a nanostructure called toroidal fullerenes (or achiral polyhex nanotorus) (see Figure 1 and Figure 2).



Figure 1. A toroidal fullerene (or achiral polyhex nanotorus) T[p,q].

The following lemma was proved in [1,30].

Lemma 2.6. The molecular graph of a polyhex nanotorus is vertex transitive.

The following is a direct consequence of Corollary 2.5 and Lemma 2.6.

**Corollary 2.7.** *Let T be a molecular graph of a polyhex nanotorus. Then* 

$$\mathcal{E}(T) = LE_{\mathrm{Tr}}(T) = LE_t(T) = LE_{deg^2}(T) = LE_{deg}(T) = LE_{\varepsilon}(T)$$

**Concluding Remarks:** In this paper by considering some vertex weights, some topological indices appear in Laplcian graph energy and average weight. Note that several other vertex weight and thus their corresponding Laplacian graph energy could be defined. For example

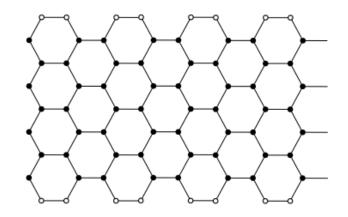


Figure 2. A 2-dimensional lattice for an achiral polyhex nanotorus T[p,q].

if we define the weight of an arbitrary vertex *u* as  $deg(u)^3$ , whose average one is  $\frac{F(G)}{n}$ , where F(G) is referred to as forgotten Zagreb index.

Acknowledgements: We are grateful to the referees for the careful reading of this paper.

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Citation: R. Sharafdini, H. Panahbar, Vertex weighted Laplacian graph energy and other topological indices , J. Disc. Math. Appl. 8(4) (2023) 177–185.

🔍 https://doi.org/10.22061/jdma.2023.524



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